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Intelligent Networked Teleoperation Control

 Springer

Zhijun Li and

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This book describes a unified framework for networked teleoperation systems involving multiple research fields: networked control systems for linear and nonlinear forms, bilateral teleoperation, trilateral teleoperation, multilateral teleoperation and cooperative teleoperation. The ideas and outcomes outlined are easy to understand, even for readers pretty new to the subject. control and robotics. It closely examines networked control as a field at the intersection of systems & As such, the reserve offers a very important reference work for researchers and engineers in the areas of systems & control and robotics and presents numerous experimental case studies on testbeds for robotic systems, including networked haptic devices, robotic network systems and sensor network systems.



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