Lecture Notes in Control and Information Sciences

Edited by M.Thoma and A.Wyner

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Algebraic Theory of Linear Feedback Systems with Full and Decentralized Compensators

Springer-Verlag Berlin Heidelberg GmbH

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Algebraic Theory of Linear Feedback Systems with Full and Decentralized Compensators (Lecture Notes in Control and Information Sciences)

The algebraic theory of linear, time-invariant, multiinput-multioutput (MIMO) feedback systems has developed rapidly during the past 10 years. it is suitable for both continuous-time and discrete-time lumped-parameter system models, and many of its results apply right to distributed-parameter systems. The factorization strategy is easy and elegant; This quantity streamlines the algebreaic approach to the evaluation and synthesis of linear time-invariant MIMO feedback systems.

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